

## SPICE Modeling Report

# 4.0 V to 17 V Input, 3 A Integrated MOSFET Single Synchronous Buck DC/DC BD9D300MUV

## General Description

In this report, the characteristics that can be confirmed by the simulation using the SPICE model of the regulator IC BD9D300MUV will be described.

## Simulation Environment

- Circuit Simulator : PSpice / Cadence Design System, Inc.
- Version Information : 17.2-2016
- OS Information : Windows 10 64-bit Edition

## File Information

- Library File Name : BD9D300MUV.lib
- Symbol File Name : BD9D300MUV.olb
- Subcircuit and Symbol

**Table 1 Correspondence Table**

Product Name	Subcircuit	Symbol
BD9D300MUV	BD9D300MUV (Model for Transient Analysis)	BD9D300MUV
		BD9D300MUV_CAD (Note2)
	BD9D300MUV_AVE (Note1) (Model for AC Analysis)	BD9D300MUV_AVE (Note3)
		BD9D300MUV_AVE_CAD (Note2) (Note3)

(Note 1) BD9D300MUV\_AVE is the spice macro model for Frequency Characteristic (AC simulation). Refer to Page 10 to 11 for simulation detail.

(Note 2) Symbol with \_CAD at the end of the name conform to IEC60617, and were designed so that signals flow from left to right.

(Note 3) Pin information for BD9D300MUV\_AVE is same like Table 2.

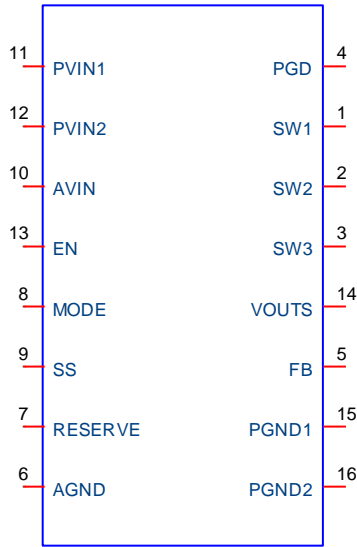
## Caution

- These model characteristics are specifically at Ta = 25 °C. Thus, the simulation result with temperature variances may significantly differ from the result with the one done at actual application board (actual measurement).
- The simulation result and characteristics described in this report may differ depending on the board design. It is recommended to perform the measurement on the actual board to verify the result.
- The values from the simulation results are not guaranteed. Use these results as a guide for your design.
- Actual measurement was done using a specific sample, thus the measured data is just as a reference.

BD9D300MUV Spice Model

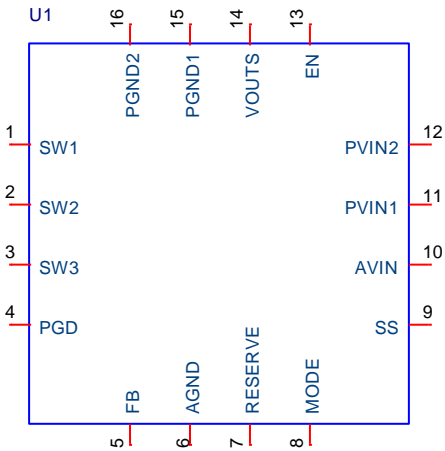
Pin Information

U1



BD9D300MUV

Figure 1 Symbol of BD9D300MUV



BD9D300MUV\_CAD

Figure 2 Symbol of BD9D300MUV\_CAD

Table 2 Subcircuit Pin Table

Pin No.	Pin Name	Pin No.	Pin Name
1.	SW1	9.	SS
2.	SW2	10.	AVIN
3.	SW3	11.	PVIN1
4.	PGD	12.	PVIN2
5.	FB	13.	EN
6.	AGND	14.	VOUTS
7.	RESERVE	15.	PGND1
8.	MODE	16.	PGND2

Model Parameter

Table 3 Model Parameter Table

Parameter	Default Value	Description
BD9D300MUV_AVE		
v_vo	5	On Duty parameter for the Numerator.
v_vin	12	On Duty parameter for the Denominator. On Duty is given as { v_vo / v_vin }.

Verifiable Characteristics

- Electrical Characteristics (vs. Datasheet) .....4
- Characteristic in SPICE (vs. Measured Waveform).....6
  - BD9D300MUV
    - ✓ Steady State (Vin = 12 V, Vout = 5 V) .....6
    - ✓ Steady State (Vin = 12 V, Vout = 3.3 V).....7
    - ✓ Load Response (Vin = 12 V, Vout = 5 V) .....8
    - ✓ Load Response (Vin = 12 V, Vout = 3.3 V).....9
  - BD9D300MUV\_AVE
    - ✓ Frequency Characteristic (Vin = 12 V, Vout = 5 V) ..... 10
    - ✓ Frequency Characteristic (Vin = 12 V, Vout = 3.3 V) ..... 11

## Electrical Characteristics (vs. Datasheet)

Table 4 Electrical Characteristics Comparison

(Unless otherwise specified Ta = 25 °C, V<sub>PVIN</sub> = V<sub>AVIN</sub> = 12 V, V<sub>EN</sub> = 5 V, V<sub>MODE</sub> = GND)

Parameter	Modeled (Note1)	Design Value		Unit	Error	Condition
		Datasheet	SPICE			
Power Supply (AVIN)						
Shutdown Current	Yes	3	3	μA	0%	V <sub>EN</sub> = 0 V
Operating Quiescent Current	Yes	20	20	μA	0%	I <sub>OUT</sub> = 0 A, No switching
UVLO Detection Threshold Voltage	Yes	3.6	3.6	V	0%	V <sub>IN</sub> falling
UVLO Hysteresis Voltage	Yes	200	200	mV	0%	
Enable						
EN Input High Level Voltage	Yes	-	0.55	V	-	
EN Input Low Level Voltage	Yes	-	0.45	V	-	
EN Input Current	Yes	-	0	μA	-	
Reference Voltage, Error Amplifier, Soft Start						
FB threshold Voltage	Yes	0.8	0.8	V	0%	
FB Input Current	Yes	1	1	nA	0%	V <sub>FB</sub> = 0.8 V
Soft Start Charge Current	Yes	2.5	2.5	μA	0%	
Internal Soft Start Time	Yes	1	1	ms	0%	
Control						
MODE Input High Level Voltage	Yes	-	0.65	V	-	
MODE Input Low Level Voltage	Yes	-	0.55	V	-	
On Time	Yes	333	333	ns	0%	V <sub>OUT</sub> = 5.0 V
Power Good						
Power Good Rising Threshold Voltage	Yes	95	95	%	0%	V <sub>FB</sub> rising, V <sub>PGDR</sub> = V <sub>FB</sub> / V <sub>FBTH</sub> X 100
Power Good Falling Threshold Voltage	Yes	90	90	%	0%	V <sub>FB</sub> falling, V <sub>PGDF</sub> = V <sub>FB</sub> / V <sub>FBTH</sub> X 100
PGD Output Leakage Current	Yes	0	0	nA	0%	V <sub>PGD</sub> = 5 V
PGD MOSFET ON Resistance	Yes	100	100	Ω	0%	
PGD Low Level Voltage	Yes	0.2	0.2	V	0%	I <sub>PGD</sub> = 2 mA
SW (MOSFET)						
High-Side FET ON Resistance	Yes	110	110	mΩ	0%	
Low-Side FET ON Resistance	Yes	50	50	mΩ	0%	
High-Side Output Leakage Current	Yes	0	0	μA	0%	No switching
Low-Side Output Leakage Current	Yes	0	0	μA	0%	No switching

(Continued)

Continued

Parameter	Modeled <i>(Note 1)</i>	Design Value		Unit	Error	Condition
		Datasheet	SPICE			
Protection						
Output OVP Detection Voltage	Yes	120	120	%	0%	$V_{FB}$ rising, $V_{OVPH} = V_{FB} / V_{FBTH} \times 100$
Output OVP Release Voltage	Yes	115	115	%	0%	$V_{FB}$ falling, $V_{OVPL} = V_{FB} / V_{FBTH} \times 100$
Low-Side FET Over Current Detection Current <i>(Note 2)</i>	Yes	3.8	3.8	A	0%	

(Note 1) Yes: Model available (supported), No: Model not available (not supported).

(Note 2) No tested on outgoing inspection.

## Characteristic in SPICE (vs. Measured Waveform)

1. Steady State ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )

## Simulation Setting

Type: Transient

Run Time: 3 ms

(Maximum Step Size: 10 ns)

PARAMETERS:

bias = 0.52

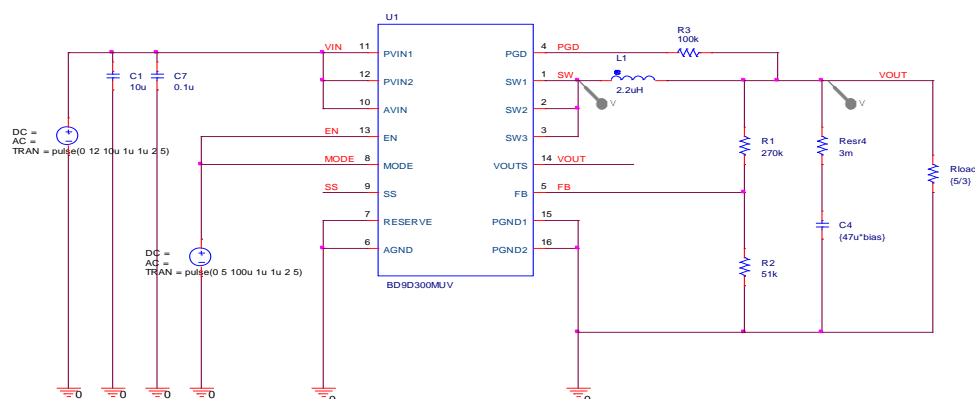
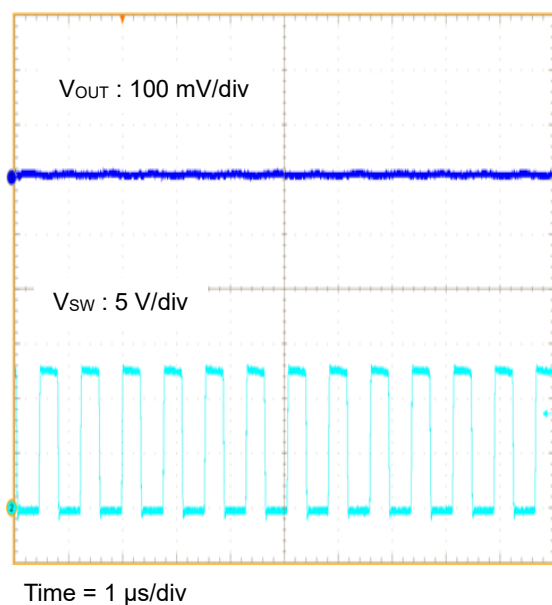
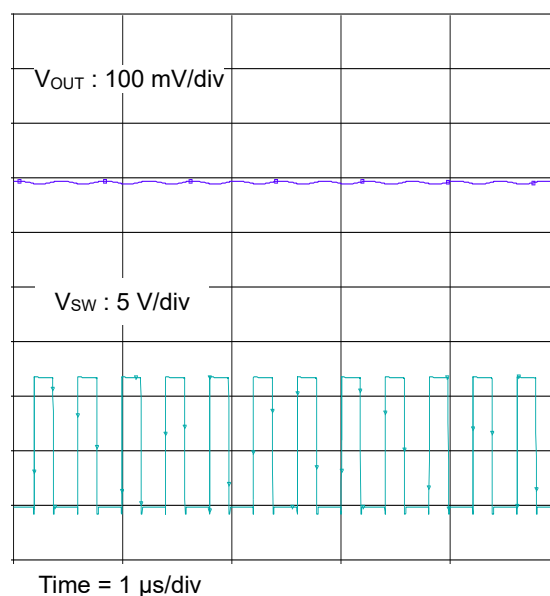
Figure 3.  
Simulation Schematic 1Figure 4.  
Steady State ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )  
(Measured Waveform)Figure 5.  
Steady State ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )  
(SPICE Simulation)

Table 5 Characteristics Comparison

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Switching Frequency	1.25	1.24	MHz	-0.8 %	$V_{IN} = 12\text{ V}$ , $V_{OUT} = 5\text{ V}$ , $I_{OUT} = 3\text{ A}$ MODE = High

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.

(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed, PCB pattern and mounting condition of each on-board parts.

2. Steady State (Vin = 12 V, Vout = 3.3 V)

Simulation Setting  
Type: Transient  
Run Time: 3 ms  
(Maximum Step Size: 10 ns)

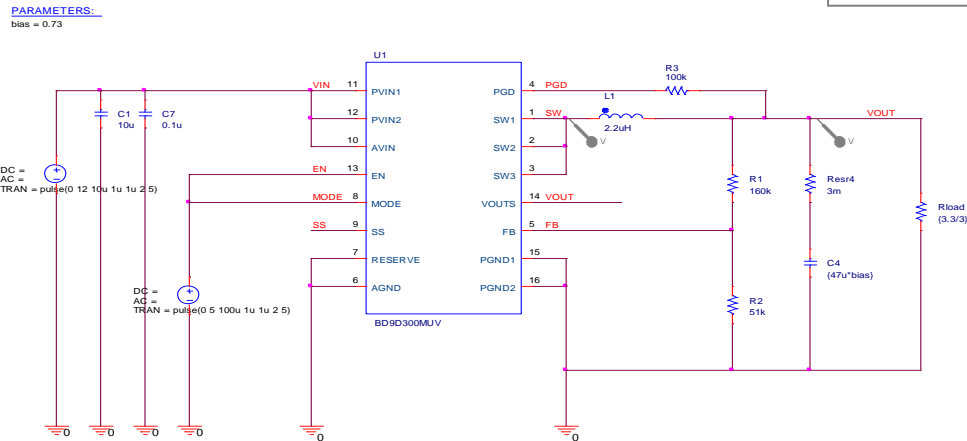


Figure 6.  
Simulation Schematic 2

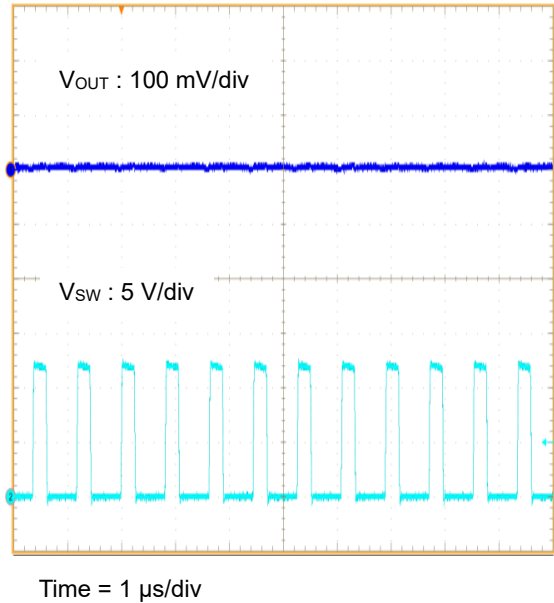


Figure 7.  
Steady State (Vin = 12 V, Vout = 3.3 V)  
(Measured Waveform)

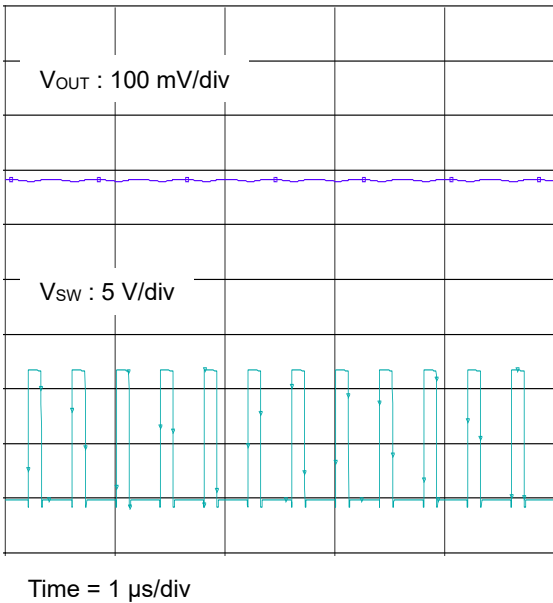


Figure 8.  
Steady State (Vin = 12 V, Vout = 3.3 V)  
(SPICE Simulation)

Table 6 Characteristics Comparison

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Switching Frequency	1.25	1.25	MHz	0.0 %	V <sub>IN</sub> = 12 V, V <sub>OUT</sub> = 3.3 V, I <sub>OUT</sub> = 3 A MODE = High

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.  
(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed,  
PCB pattern and mounting condition of each on-board parts.

3. Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )

## Simulation Setting

Type: Transient

Run Time: 12 ms

(Maximum Step Size: 10 ns)

## PARAMETERS:

bias = 0.52

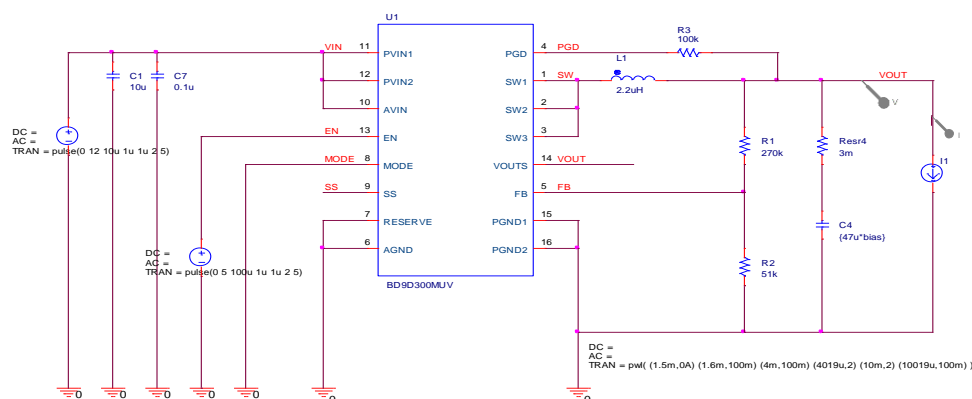
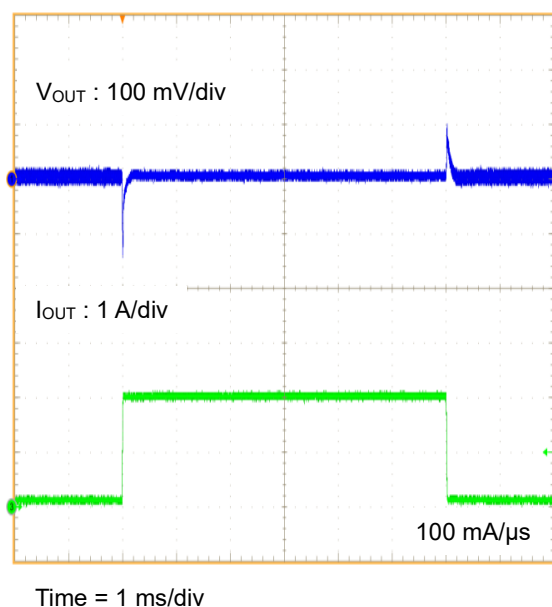
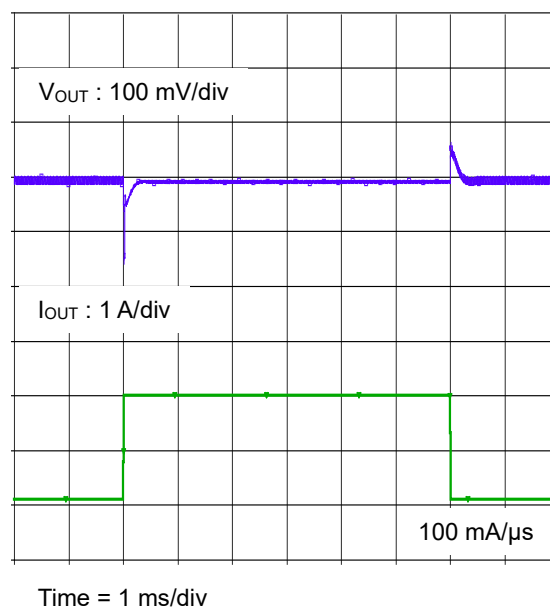
Figure 9.  
Simulation Schematic 3Figure 10.  
Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )  
(Measured Waveform)Figure 11.  
Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 5\text{ V}$ )  
(SPICE Simulation)

Table 7 Characteristics Comparison

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Undershoot	152.4	147.9	mV	-3.0 %	$V_{IN} = 12\text{ V}$ , $V_{OUT} = 5\text{ V}$ , $I_{OUT} = 0.1\text{ A to } 2\text{ A}$ , MODE = Low
Overshoot	85.6	76.7	mV	-10.4 %	

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.

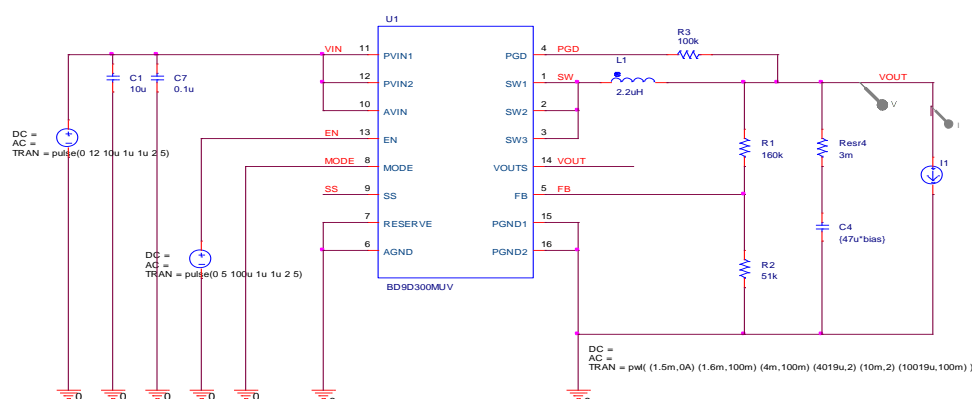
(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed, PCB pattern and mounting condition of each on-board parts.



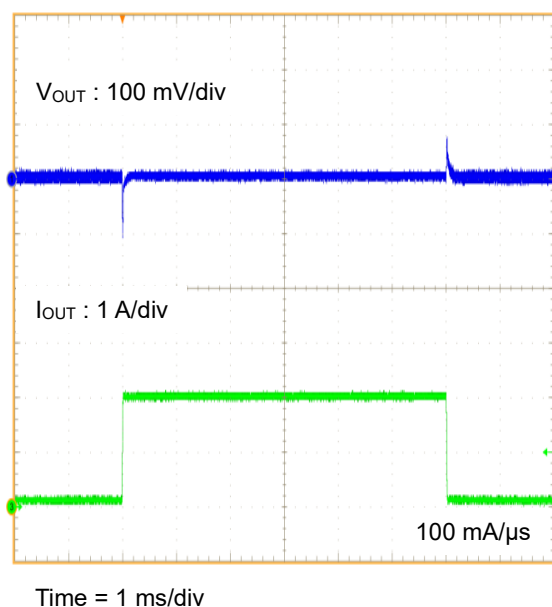
4. Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 3.3\text{ V}$ )

**Simulation Setting**  
 Type: Transient  
 Run Time: 12 ms  
 (Maximum Step Size: 10 ns)

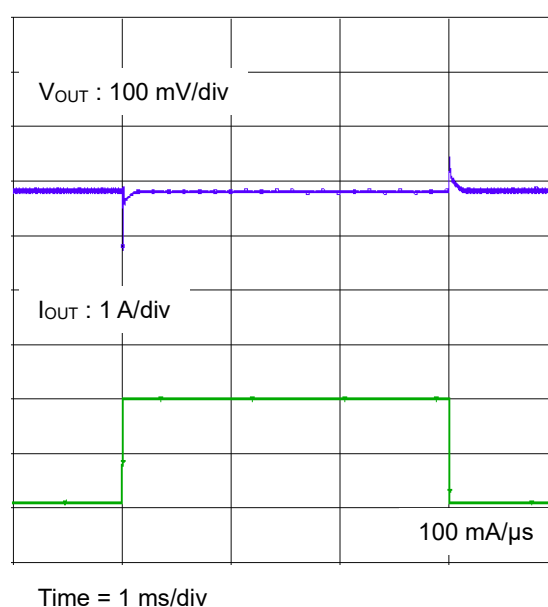
**PARAMETERS:**  
 bias = 0.73



**Figure 12.**  
**Simulation Schematic 4**



**Figure 13.**  
**Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 3.3\text{ V}$ )**  
**(Measured Waveform)**



**Figure 14.**  
**Load Response ( $V_{in} = 12\text{ V}$ ,  $V_{out} = 3.3\text{ V}$ )**  
**(SPICE Simulation)**

**Table 8 Characteristics Comparison**

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Undershoot	112.4	111.1	mV	-1.2 %	$V_{IN} = 12\text{ V}$ , $V_{OUT} = 3.3\text{ V}$ , $I_{OUT} = 0.1\text{ A to } 2\text{ A}$ , MODE = Low
Overshoot	73.6	61.4	mV	-16.6 %	

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.

(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed, PCB pattern and mounting condition of each on-board parts.

5. Frequency Characteristic (Vin = 12 V, Vout = 5 V)

Simulation Setting

Type: AC

Frequency Range:

1 kHz to 1 MHz

(Points/Decade: 20)

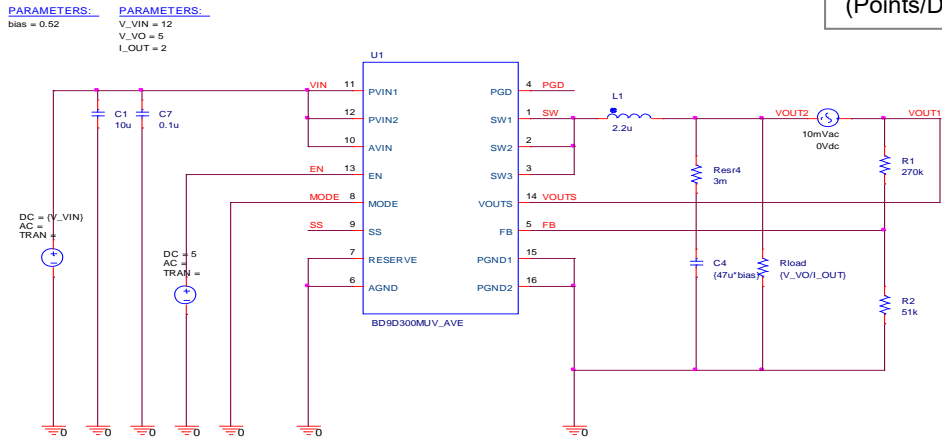


Figure 15.  
Simulation Schematic 5

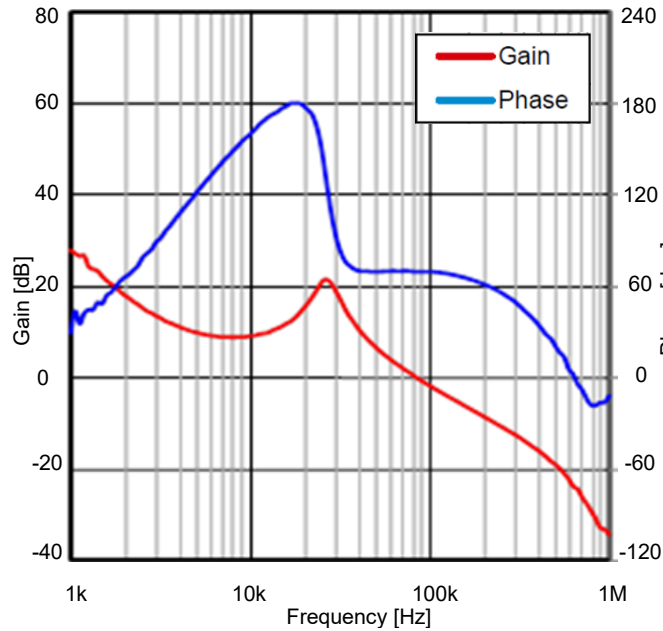


Figure 16.  
Frequency Characteristic (Vin = 12 V, Vout = 5 V)  
(Measured Waveform)

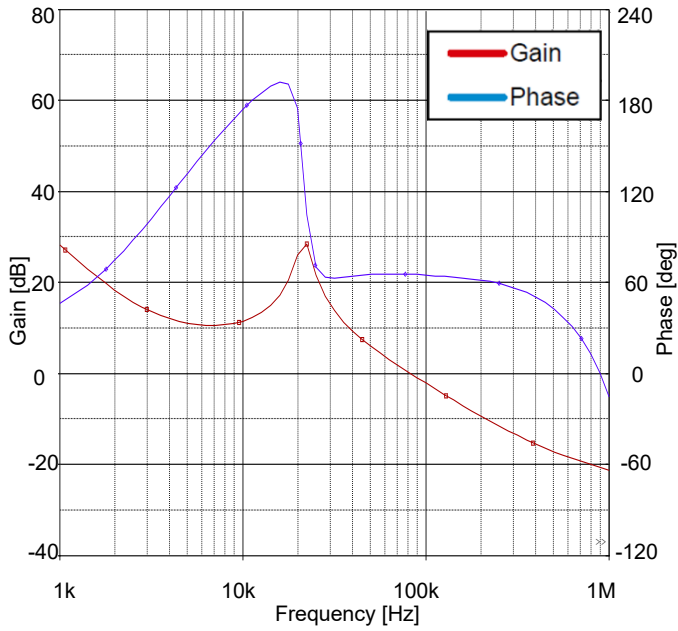


Figure 17.  
Frequency Characteristic (Vin = 12 V, Vout = 5 V)  
(SPICE Simulation)

Table 9 Characteristics Comparison

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Phase Margin	72	65.5	degree	-9.0 %	V <sub>IN</sub> = 12 V, V <sub>OUT</sub> = 5 V, I <sub>OUT</sub> = 2 A, MODE = Low
Crossover Frequency	83	83.1	kHz	0.1 %	

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.  
(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed,  
PCB pattern and mounting condition of each on-board parts.

6. Frequency Characteristic (Vin = 12 V, Vout = 3.3 V)

Simulation Setting  
Type: AC  
Frequency Range:  
1 kHz to 1 MHz  
(Points/Decade: 20)

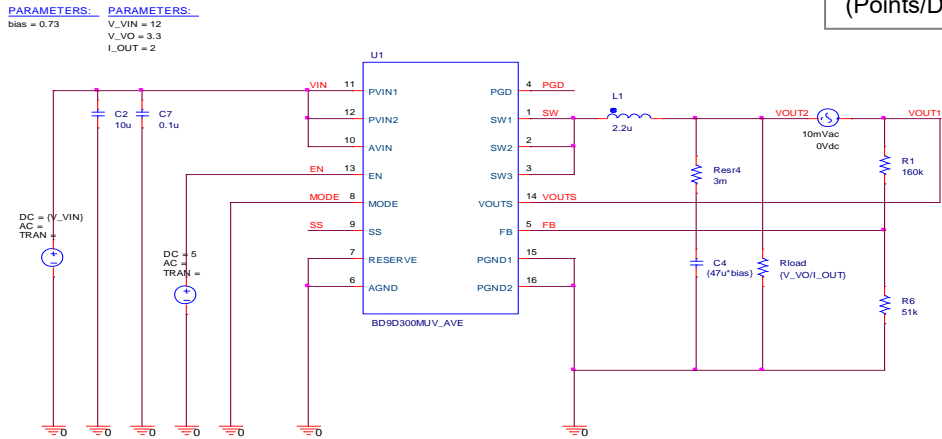


Figure 18.  
Simulation Schematic 6

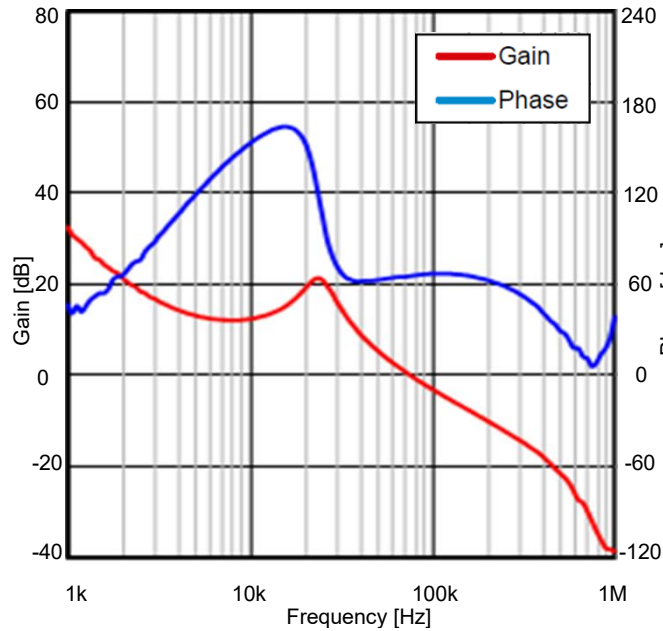


Figure 19.  
Frequency Characteristic (Vin = 12 V, Vout = 3.3 V)  
(Measured Waveform)

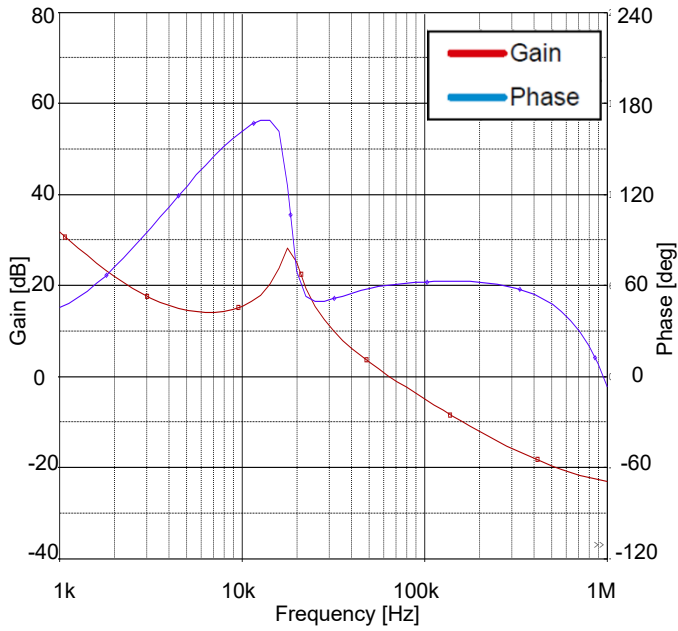


Figure 20.  
Frequency Characteristic (Vin = 12 V, Vout = 3.3 V)  
(SPICE Simulation)

Table 10 Characteristics Comparison

Parameter	Measured Result (Note1)(Note2)	SPICE Simulation Result	Unit	Error	Condition
Phase Margin	66	60.7	degree	-8.0 %	V <sub>IN</sub> = 12 V, V <sub>OUT</sub> = 3.3 V, I <sub>OUT</sub> = 2 A, MODE = Low
Crossover Frequency	73	64.9	kHz	-11.1 %	

(Note 1) The above data is based on a specific sample and it is not a guaranteed value.  
(Note 2) These characteristics depend on some dynamic characteristics of external components, input signal speed,  
PCB pattern and mounting condition of each on-board parts.

**Revision History**

Date	Revision	Changes
May.2022	001	New Release

## Notes

- 1) The information contained herein is subject to change without notice.
- 2) Before you use our Products, please contact our sales representative and verify the latest specifications :
- 3) Although ROHM is continuously working to improve product reliability and quality, semiconductors can break down and malfunction due to various factors.  
Therefore, in order to prevent personal injury or fire arising from failure, please take safety measures such as complying with the derating characteristics, implementing redundant and fire prevention designs, and utilizing backups and fail-safe procedures. ROHM shall have no responsibility for any damages arising out of the use of our Products beyond the rating specified by ROHM.
- 4) Examples of application circuits, circuit constants and any other information contained herein are provided only to illustrate the standard usage and operations of the Products. The peripheral conditions must be taken into account when designing circuits for mass production.
- 5) The technical information specified herein is intended only to show the typical functions of and examples of application circuits for the Products. ROHM does not grant you, explicitly or implicitly, any license to use or exercise intellectual property or other rights held by ROHM or any other parties. ROHM shall have no responsibility whatsoever for any dispute arising out of the use of such technical information.
- 6) The Products specified in this document are not designed to be radiation tolerant.
- 7) For use of our Products in applications requiring a high degree of reliability (as exemplified below), please contact and consult with a ROHM representative : transportation equipment (i.e. cars, ships, trains), primary communication equipment, traffic lights, fire/crime prevention, safety equipment, medical systems, servers, solar cells, and power transmission systems.
- 8) Do not use our Products in applications requiring extremely high reliability, such as aerospace equipment, nuclear power control systems, and submarine repeaters.
- 9) ROHM shall have no responsibility for any damages or injury arising from non-compliance with the recommended usage conditions and specifications contained herein.
- 10) ROHM has used reasonable care to ensure the accuracy of the information contained in this document. However, ROHM does not warrants that such information is error-free, and ROHM shall have no responsibility for any damages arising from any inaccuracy or misprint of such information.
- 11) Please use the Products in accordance with any applicable environmental laws and regulations, such as the RoHS Directive. For more details, including RoHS compatibility, please contact a ROHM sales office. ROHM shall have no responsibility for any damages or losses resulting from non-compliance with any applicable laws or regulations.
- 12) When providing our Products and technologies contained in this document to other countries, you must abide by the procedures and provisions stipulated in all applicable export laws and regulations, including without limitation the US Export Administration Regulations and the Foreign Exchange and Foreign Trade Act.
- 13) This document, in part or in whole, may not be reprinted or reproduced without prior consent of ROHM.



Thank you for your accessing to ROHM product informations.  
More detail product informations and catalogs are available, please contact us.

## ROHM Customer Support System

<http://www.rohm.com/contact/>